

# NSF Simulation Optimization Workshop

Lee Schruben, LeeS@Berkeley.edu

- **Black boxes**

A (possibly new) algorithm for *Attainable* global optimization  
Retrospective Optimization & clones (SPO, SAA,...).

- **Gray boxes**

Frequency Domain Factor Screening  
Experiment in the Model – simultaneous replication  
Meta-model generation  
Time Dilation (orders of magnitude improvement!)

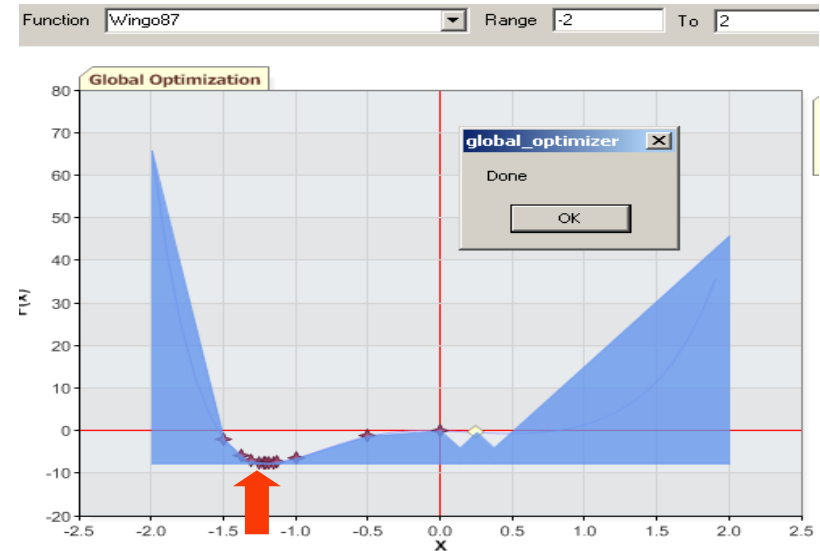
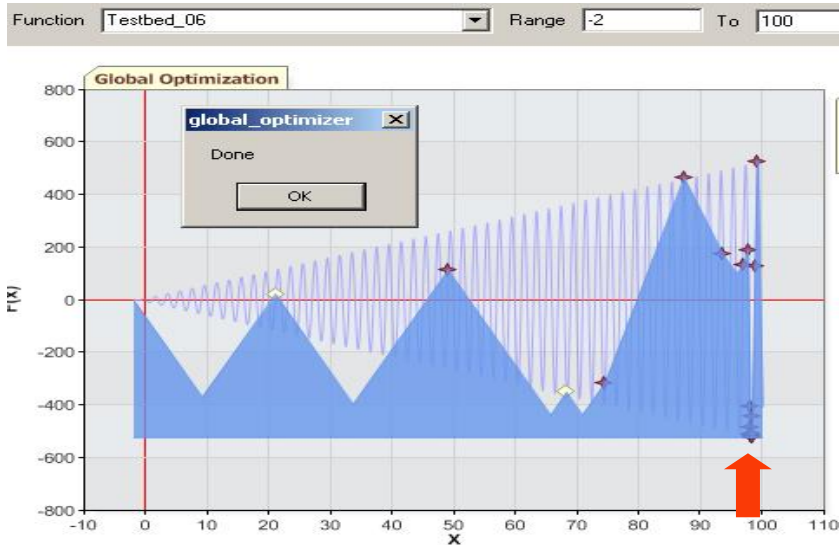
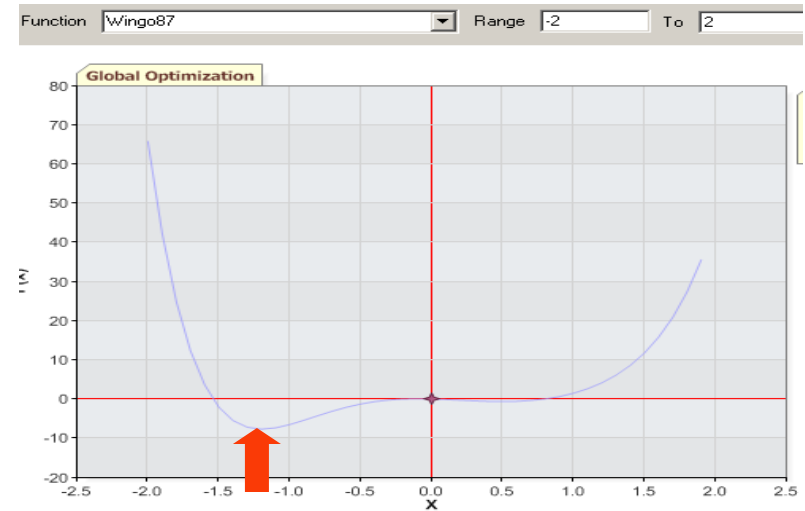
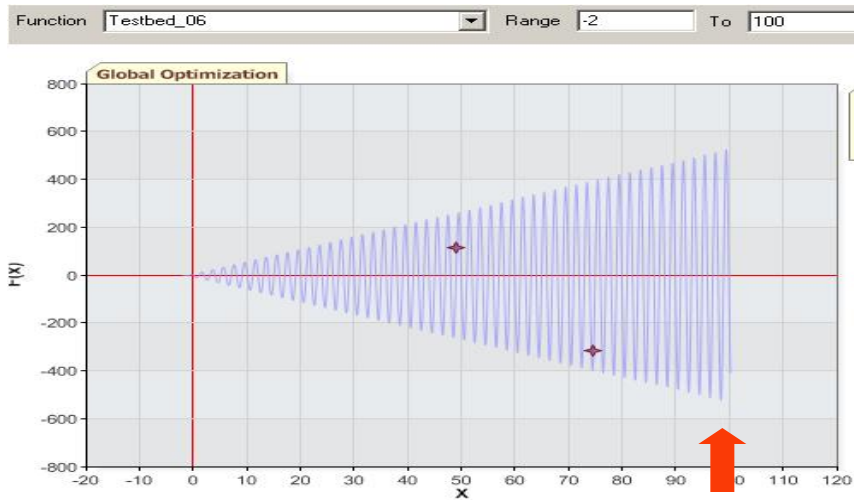
- **Clear boxes**

Resource-driven, Activity Interaction, Dynamic Tagging, VRTs  
DES ↔ Linear Programs (opt and sensitivity)

# Current Research: Black Box Optimization

Algorithm: Select most likely achievable new minimum...(min energy)

Some 1-D examples

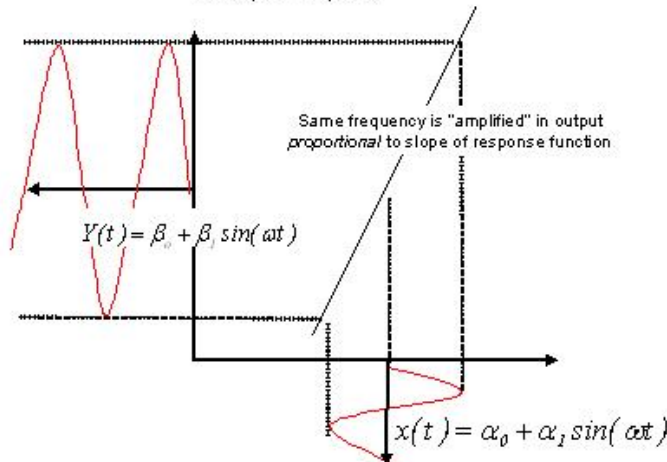


# Gray Boxes (Most simulations?)

## FDE

Controllable/Observable states

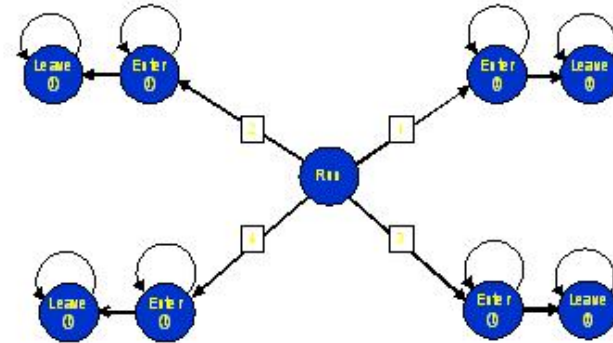
Linear system response



Factor	Range of Values	Type	Frequency
Mean Storm Time	3 to 5	continuous	0.00197
Distn of Storm Times	Uniform/Exponential	qualitative	0.00787
Mean Arrival Rate	8 to 14	continuous	0.01969
Distn of Arrivals	Uniform/Exponential	qualitative	0.03346
Number of Tugs	1 to 3	discrete	0.05709
Number of Berths	3 to 6	discrete	0.10236
Mean Ship Loading Times	Mean(ship type) ± 8	continuous	0.13189
Distn of Ship Loading Times	Uniform/Exponential	qualitative	0.1732
Distn of Ship Types	Multinomial CDF 1,2	qualitative	0.23984
Mean Inter-Storm Time	24 to 72	continuous	0.32283
Distn of Inter-Storm Times	Uniform/Exponential	qualitative	0.40254

## Meta Model Output

Controlling time



Run all design points simultaneously

Controllable/Observable states

## Meta-model Generation

Since

$$\hat{\beta}^{(p)} = \sum_{j=1}^k \alpha_j^{(p)} \bar{Y}_j = \frac{1}{n} \sum_{j=1}^k \alpha_j^{(p)} \sum_{i=1}^n Y_{i,j} = \frac{1}{n} \sum_{i=1}^n \hat{\beta}_i^{(p)}$$

- Replicate full experiment in single run.

$$\{Y_{i,j}\}$$

- Generate meta-model parameters as output.

$$\{\hat{\beta}_i^{(p)} : \hat{\beta}_i^{(p)} = \sum_{j=1}^k \alpha_j^{(p)} Y_{i,j}\}$$

The meta-model is the output,  
not computed from the output.

# Gray Boxes- time dilation

Controlling time

## Time Dilation

Run simultaneous replications at various design points

Change the time scale to spend less time simulating poor factor settings

Spawn new factor settings when it makes sense

## Focus the run on the winners

Controlling time

## Comparisons\*

	Parts required	Ratio of parts required comp. to time dilation	Total cost to decision
Arena	325,00	10	\$130,000
ProModel	2,600,000	80	\$1,040,000
Witness	330,000	10	\$132,000
ProModel, new version	760,000	23	\$304,000

Time Dilation experiment cost **\$ 8,790.**

\*Law, A. M. and M. G. McCrossin. 2000. Simulation-based optimization. *Proceedings of the 2000 Winter Simulation Conference*, 46-49.

## Black Box “*Simulation*” Research: are we missing something?

In a simulated environment one can control

- Speed – (adaptive entity tagging)
- State Observability/Control (FDE, MM output)
- Uncertainty (Corr. Ind., Bayesian bootstrap)
- Time scale (Time dilation)
- Future (Retrospective optimization & clones)
- Resolution (Implicit tagging, M<sup>4</sup>s)
- Causality (LP models of DEDS,  
Virtual resources, queueing duality)

**How can Simulation Research further exploit  
the advantages of simulation?**