



Stochastic Optimization: The Present and Future of OR

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Outline



- Overview
- Examples
 - Vehicle Allocation
 - Financial planning
 - Manufacturing
- Methods
- View ahead

Overview



■ Stochastic optimization

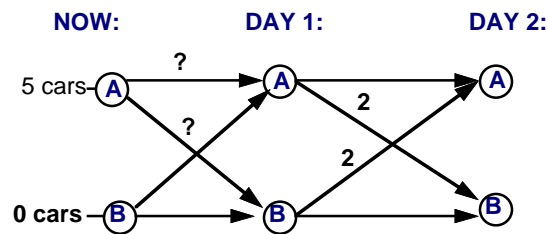
- Traditional
 - » Small problems
 - » Impractical
- Current
 - » Integrate with large-scale optimization (stochastic programming)
 - » Practical examples
 - » Expanding rapidly

Vehicle Allocation



■ Decision:

» How to position empty freight cars?



DEMAND: DAY 1: B to A: Mean Value=2
 DAY 1: A to B: Mean Value=2

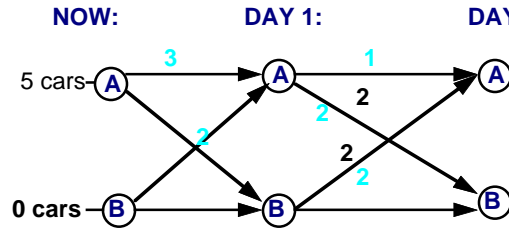
Vehicle Allocation: Mean Value Solution



Parameters: COST: 0.5 per empty car from A to B
 REVENUE: 1.5 per full car from A to B

- Maximize: Revenue-Cost

» MOVE TWO EMPTY CARS FROM A to B



RESULT: Net 2: A to B; Net 2: B to A
 TOTAL(MV) = 4

Expectation of Mean Value

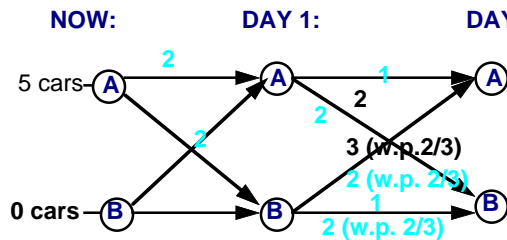


Suppose: Demand is Random (Expectation from A to B=2)

- 0 from A to B with prob. 1/3
- 3 from A to B with prob. 2/3

- Find: Expected (Revenue-Cost)

» MOVE Two EMPTY CARS FROM A to B



Expected Value: Net 2: A to B; Net 2: B to A (w.p. 2/3)
 -1: B to A (w.p. 1/3)

TOTAL (EMV): 3

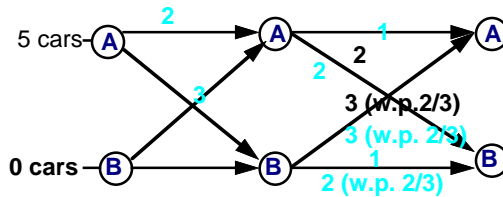
Stochastic Program Solution

Suppose: Demand is **Random** (as before)

GOAL: A solution to obtain highest **expected** value

- **Maximize: Expected (Revenue-Cost)**

» **MOVE Three EMPTY CARS FROM A to B**



Expected Value: Net 2: A to B; Net 3: B to A (w.p. 2/3)
-1.5 : B to A (w.p. 1/3)

TOTAL (RP): 3.5
RP=Recourse Problem

INFORMATION and MODEL VALUE

■ INFORMATION VALUE:

- FIND Expected Value with Perfect Information or Wait-and-See (WS) solution:
 - » Know demand: if 3, send 3 from A to B If 0, send 0 from A to B:
 - » Earn: $2 \text{ (AtoB)} + (2/3) (3) + (1/3)0 = 4 = \text{WS}$
- Expected Value of Perfect Information (EVPI):
 - » $\text{EVPI} = \text{WS} - \text{RP} = 4 - 3.5 = 0.5$
 - » Value of knowing future demand precisely

■ MODEL VALUE:

- FIND EMV, RP
- Value of the Stochastic Solution (VSS):
 - » $\text{VSS} = \text{RP} - \text{EMV} = 3.5 - 3 = 0.5$
 - » Value of using the correct optimization model

INFORMATION/MODEL OBSERVATIONS



- EVPI and VSS:
 - ALWAYS ≥ 0 ($WS \geq RP \geq EMV$)
 - OFTEN DIFFERENT ($WS=RP$ but $RP > EMV$ and vice versa)
 - FIT CIRCUMSTANCES:
 - » COST TO GATHER INFORMATION
 - » COST TO BUILD MODEL AND SOLVE PROBLEM
- MEAN VALUE PROBLEMS:
 - MV IS OPTIMISTIC ($MV=4$ BUT $EMV=3$, $RP=3.5$)
 - » ALWAYS TRUE IF CONVEX AND RANDOM
 - » CONSTRAINT PARAMETERS
 - VSS LARGER FOR SKEWED DISTRIBUTIONS/COSTS

STOCHASTIC PROGRAM



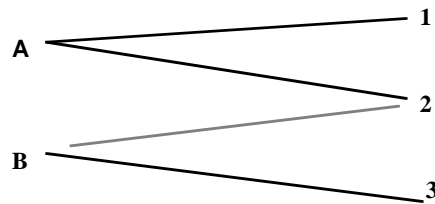
- **ASSUME:** Random demand on AB and BA
- **GOAL:** maximize **expected** profits
 - (risk neutral)
- **DECISIONS:** x_{ij} - empty from i to j
 - $y_{ij}(s)$ - full from i to j in scenario s (**RECOURSE**)
 - (prob. $p(s)$)
- **FORMULATION:**

$$\begin{aligned}
 & \text{Max } -0.5x_{AB} + \sum_{s=s1,s2} p(s) (1.5 y_{AB}(s) + 1.5 y_{BA}(s)) \\
 \text{s.t. } & x_{AB} + x_{AA} = 5 \quad \text{(Initial)} \\
 & -x_{AB} + y_{BA}(s) \leq 0 \quad \text{(Limit BA)} \\
 & -x_{AA} + y_{AB}(s) \leq 0 \quad \text{(Limit AB)} \\
 & y_{BA}(s) \leq DBA(s) \quad \text{(Demand BA)} \\
 & + y_{AB}(s) \leq DAB(s) \quad \text{(Demand AB)} \\
 & x_{AA}, x_{AB}, y_{AA}(s), y_{AB}(s) \geq 0
 \end{aligned}$$

- **EXTENSIONS:** Multiple stages
 - Constraint/objective complexity (Powell et al.)

Manufacturing Capacity

- Where to Install Capacity for Different Models among Different Plants?



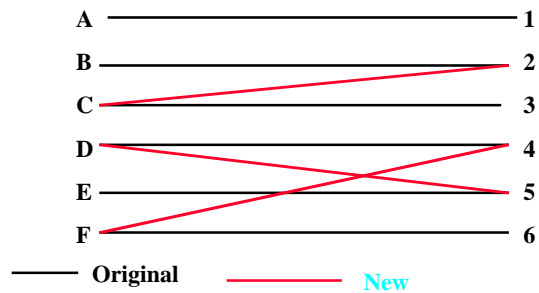
- Where to add flexibility? (multiple models)

Recourse Payoff Evaluation

- Key: Evaluate Expected Optimal with Installed Capacity
 - Must choose best mix of models assigned to plants
 - Maximize $\sum_i \text{Profit}(i) \text{ Production}(i)$
 - subject to: $\text{MaxSales}(i) \geq \sum_j \text{Production}(i \text{ at } j)$
 - $\sum_i \text{Production}(i \text{ at } j) \leq \text{Capacity}(i)$
 - $\text{Production}(i \text{ at } j) \leq \text{Capacity}(i \text{ at } j)$
 - $\text{Production}(i \text{ at } j) \geq 0$
- Transportation Problem
- Need $\text{MaxSales}(i)$ - random - unknown distribution
 - $\text{Capacity}(i \text{ at } j)$ - Decision in First Stage

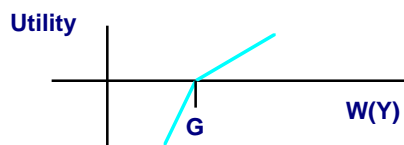
Solution Results

- Model Data: from Graves/Jordan
- Vary: Model Lifetimes
 - Longer => More flexibility
- Start: 1 Year



Financial Planning

- GOAL: Accumulate \$G for tuition Y years from now
- Assume:
 - \$ $W(0)$ - initial wealth
 - K - investments
 - concave utility (piecewise linear)



RANDOMNESS: returns $r(k,t)$ - for k in period t
 where $Y \rightarrow T$ decision periods

FORMULATION



- SCENARIOS: $\sigma \in \Sigma$
 - Probability, $p(\sigma)$
 - Groups, S^1, \dots, S^t_{st} at t
- MULTISTAGE STOCHASTIC NLP FORM:

$$\begin{aligned} \max \quad & \sum_{\sigma} p(\sigma) (U(W(\sigma, T))) \\ \text{s.t. (for all } \sigma): & \sum_k x(k, 1, \sigma) = W(o) \text{ (initial)} \\ & \sum_k r(k, t-1, \sigma) x(k, t-1, \sigma) - \sum_k x(k, t, \sigma) = 0, \text{ all } t > 1; \\ & \sum_k r(k, T-1, \sigma) x(k, T-1, \sigma) - W(\sigma, T) = 0, \text{ (final);} \\ & x(k, t, \sigma) \geq 0, \text{ all } k, t; \end{aligned}$$

Nonanticipativity:

$x(k, t, \sigma') - x(k, t, \sigma) = 0$ if $\sigma', \sigma \in S^i$ for all t, i, σ', σ
 This says decision cannot depend on future.

DATA and SOLUTIONS



- ASSUME:
 - $Y=15$ years
 - $G=\$80,000$
 - $T=3$ (5 year intervals)
 - $k=2$ (stock/bonds)
- Returns (5 year):
 - Scenario A: $r(\text{stock}) = 1.25$ $r(\text{bonds}) = 1.14$
 - Scenario B: $r(\text{stock}) = 1.06$ $r(\text{bonds}) = 1.12$
- Solution:

PERIOD	SCENARIO	STOCK	BONDS
1	1-8	41.5	13.5
2	1-4	65.1	2.17
2	5-8	36.7	22.4
3	1-2	83.8	0
3	3-4	0	71.4
3	5-6	0	71.4
3	7-8	64.0	0

GENERAL MULTISTAGE MODEL



■ FORMULATION:

$$\begin{aligned} \text{MIN} \quad & E [\sum_{t=1}^T f_t(x_t, x_{t+1})] \\ \text{s.t.} \quad & x_t \in X_t \\ & x_t \text{ nonanticipative} \\ & P[h_t(x_t, x_{t+1}) \leq 0] \geq a \text{ (chance constraint)} \end{aligned}$$

EXAMPLES:

Vehicle Allocation: Linear functions, continuous or integer variables

Capacity: Linear plus integer variables

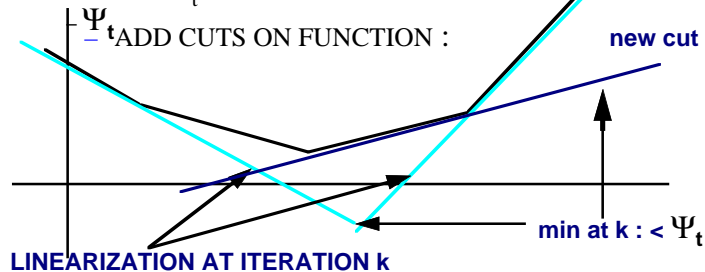
Financial Planning: Nonlinear objective, continuous variables

DECOMPOSITION METHODS



■ BENDERS IDEA

– FORM AN OUTER LINEARIZATION
OF Ψ_t



USE AT EACH STAGE TO APPROXIMATE VALUE FUNCTION

• ITERATE BETWEEN STAGES UNTIL ALL MIN = Ψ_t

DECOMPOSITION IMPLEMENTATION

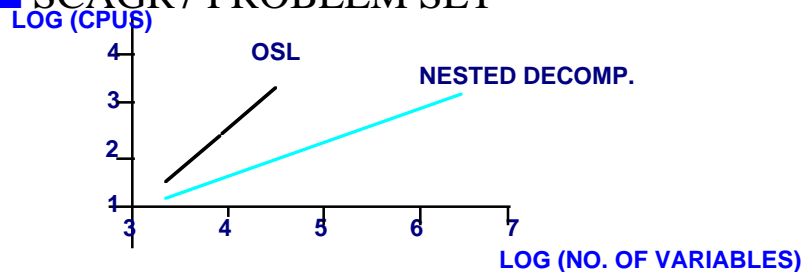


- **NESTED DECOMPOSITION**
 - LINEARIZATION OF VALUE FUNCTION AT EACH STAGE
 - DECISIONS ON WHICH STAGE TO SOLVE, WHICH PROBLEMS AT EACH STAGE
- **LINEAR PROGRAMMING SOLUTIONS**
 - USE OSL FOR LINEAR SUBPROBLEMS
 - USE MINOS FOR NONLINEAR PROBLEMS
- **PARALLEL IMPLEMENTATION**
 - USE NETWORK OF RS6000S
 - PVM PROTOCOL

RESULTS



■ SCAGR7 PROBLEM SET



PARALLEL: 60-80% EFFICIENCY IN SPEEDUP

OTHER PROBLEMS: SIMILAR RESULTS

- ONLY < ORDER OF MAGNITUDE SPEEDUP WITH STORM
- TWO-STAGES - LITTLE COMMONALITY IN SUBPROBLEMS
- STILL ABLE TO SOLVE ORDER OF MAGNITUDE LARGER PROBLEMS

View Ahead



■ New Trends

- Methods for **integer** variables
 - » Power system implementations
 - » Vehicle routing
- Integrating **simulation**
 - » Sampling with optimization
 - » On-line optimization
 - » Low-discrepancy methods

More Trends



- **Modeling** languages
 - Ability to build stochastic programs directly
 - Integrating across systems
- Using application **structure**
 - Separation of problem (dimension reduction)
 - Network properties
 - Generalized versions of convexity

Summary



- **Increasing** application base
- **Value** for solving the stochastic problem
- **Efficient** implementations
- **Opportunities** for new results