

Introduction to Stochastic Programming

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Outline

- Overview
- Examples
 - Vehicle Allocation
 - Financial planning
 - Manufacturing
- Methods
- View ahead

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Overview

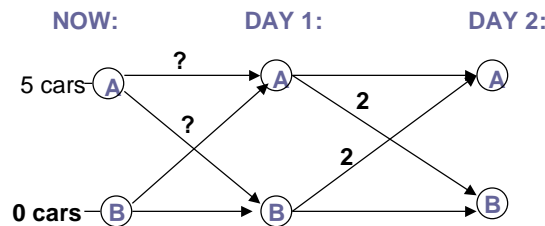
- Stochastic optimization
 - Traditional
 - Small problems
 - Impractical
 - Current
 - Integrate with large-scale optimization (stochastic programming)
 - Practical examples
 - Expanding rapidly

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Vehicle Allocation

- Decision:
 - How to position empty freight cars?



DEMAND: DAY 1: B to A:Mean Value=2
 DAY 1: A to B:Mean Value=2

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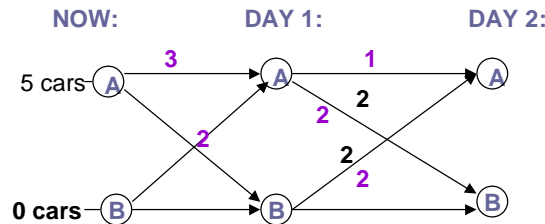
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Vehicle Allocation: Mean Value Solution

Parameters: COST: 0.5 per empty car from A to B
REVENUE: 1.5 per full car from A to B

- Maximize: Revenue-Cost

» MOVE TWO EMPTY CARS FROM A to B



RESULT: Net 2: A to B; Net 2: B to A
TOTAL(MV) = 4

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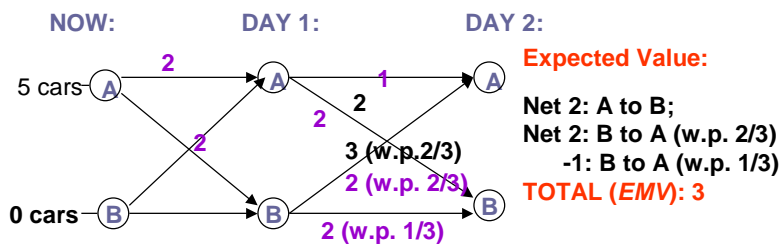
Expectation of Mean Value

Suppose: Demand is Random (Expectation from A to B=2)

- 0 from A to B with prob. 1/3
- 3 from A to B with prob. 2/3

- Find: Expected (Revenue-Cost)

» MOVE Two EMPTY CARS FROM A to B



Expected Value:

Net 2: A to B;
Net 2: B to A (w.p. 2/3)
-1: B to A (w.p. 1/3)

TOTAL (EMV): 3

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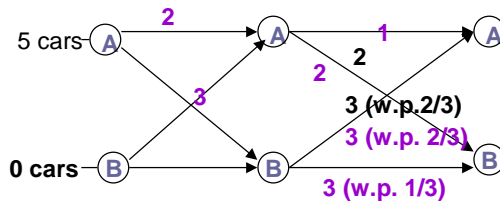
Stochastic Program Solution

Suppose: Demand is **Random** (as before)

GOAL: A solution to obtain highest **expected** value

- **Maximize: Expected (Revenue-Cost)**

» **MOVE Three EMPTY CARS FROM A to B** **Expected Value:**
 NOW: DAY 1: DAY 2:



Net 2: A to B;
 Net 3: B to A (w.p. 2/3)
 -1.5 : B to A (w.p. 1/3)
TOTAL (RP): 3.5
RP=Recourse Problem

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INFORMATION and MODEL VALUE

- **INFORMATION VALUE:**

- **FIND Expected Value with Perfect Information or Wait-and-See (WS) solution:**

- Know demand: if 3, send 3 from A to B; If 0, send 0 from A to B;
- Earn: $2 \text{ (AtoB)} + (2/3) (3) + (1/3)0 = 4 = \text{WS}$

- **Expected Value of Perfect Information (EVPI):**

- $\text{EVPI} = \text{WS} - \text{RP} = 4 - 3.5 = 0.5$
- Value of knowing future demand precisely

- **MODEL VALUE:**

- **FIND EMV, RP**
- **Value of the Stochastic Solution (VSS):**
 - $\text{VSS} = \text{RP} - \text{EMV} = 3.5 - 3 = 0.5$
 - Value of using the correct optimization model

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INFORMATION/MODEL OBSERVATIONS

- EVPI and VSS:
 - ALWAYS ≥ 0 (WS \geq RP \geq EMV)
 - OFTEN DIFFERENT (WS=RP but RP > EMV and vice versa)
 - FIT CIRCUMSTANCES:
 - COST TO GATHER INFORMATION
 - COST TO BUILD MODEL AND SOLVE PROBLEM
- MEAN VALUE PROBLEMS:
 - MV IS OPTIMISTIC (MV=4 BUT EMV=3, RP=3.5)
 - ALWAYS TRUE IF CONVEX AND RANDOM
 - CONSTRAINT PARAMETERS
 - VSS LARGER FOR SKEWED DISTRIBUTIONS/COSTS

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STOCHASTIC PROGRAM

- ASSUME: Random demand on AB and BA
- GOAL: maximize expected profits
 - (risk neutral)
- DECISIONS: x_{ij} - empty from i to j
 - $y_{ij}(s)$ - full from i to j in scenario s (RECOURSE)
 - (prob. $p(s)$)
- FORMULATION:

$$\text{Max } -0.5x_{AB} + \sum_{s=s1, s2} p(s) (1.5 y_{AB}(s) + 1.5 y_{BA}(s))$$

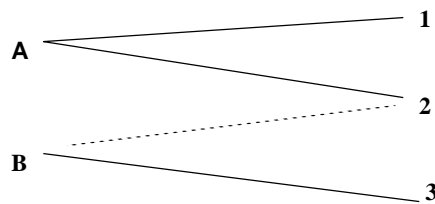
$$\text{s.t. } \begin{array}{ll} x_{AB} + x_{AA} & = 5 \text{ (Initial)} \\ -x_{AB} & + y_{BA}(s) \leq 0 \text{ (Limit BA)} \\ -x_{AA} & + y_{AB}(s) \leq 0 \text{ (Limit AB)} \\ & y_{BA}(s) \leq DBA(s) \text{ (Demand BA)} \\ & + y_{AB}(s) \leq DAB(s) \text{ (Demand AB)} \\ & x_{AA}, x_{AB}, y_{AA}(s), y_{AB}(s) \geq 0 \end{array}$$
- EXTENSIONS: Multiple stages; Constraint/objective complexity (Powell et al.)

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Manufacturing Capacity

- Where to Install Capacity for Different Models among Different Plants?



- Where to add flexibility? (multiple models)

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Recourse Payoff Evaluation

- Key: Evaluate Expected Optimal with Installed Capacity

Must choose best mix of models assigned to plants

Maximize $\sum_i \text{Profit}(i) \text{ Production}(i)$

subject to: $\text{MaxSales}(i) \geq \sum_j \text{Production}(i \text{ at } j)$

$\sum_i \text{Production}(i \text{ at } j) \leq \text{Capacity}(j)$

$\text{Production}(i \text{ at } j) \leq \text{Capacity}(i \text{ at } j)$

$\text{Production}(i \text{ at } j) \geq 0$

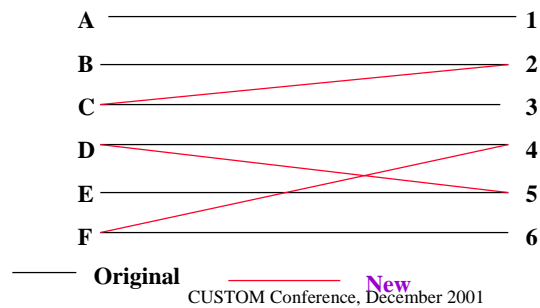
- Transportation Problem
- Need $\text{MaxSales}(i)$ - random - unknown distribution
 - $\text{Capacity}(i \text{ at } j)$ - Decision in First Stage

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Solution Results

- **Model Data:** from Graves/Jordan
- **Vary: Model Lifetimes**
 - Longer => More flexibility
- **Start: 1 Year**

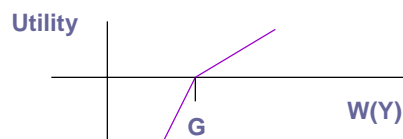


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Financial Planning

- **GOAL:** Accumulate \$G for tuition Y years from now
- **Assume:**
 - \$ $W(0)$ - initial wealth
 - K - investments
 - concave utility (piecewise linear)



RANDOMNESS: returns $r(k,t)$ - for k in period t
 where $Y \rightarrow T$ decision periods

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FORMULATION

- **SCENARIOS:** $\sigma \in \Sigma$
 - Probability, $p(\sigma)$
 - Groups, $S^t_1, \dots, S^t_{S_t}$ at t
- **MULTISTAGE STOCHASTIC NLP FORM:**

$$\begin{aligned}
 &\max \quad \sum_{\sigma} p(\sigma) (U(W(\sigma, T))) \\
 &\text{s.t. (for all } \sigma): \sum_k x(k, 1, \sigma) = W(o) \text{ (initial)} \\
 &\quad \sum_k r(k, t-1, \sigma) x(k, t-1, \sigma) - \sum_k x(k, t, \sigma) = 0, \text{ all } t > 1; \\
 &\quad \sum_k r(k, T-1, \sigma) x(k, T-1, \sigma) - W(\sigma, T) = 0, \text{ (final);} \\
 &\quad x(k, t, \sigma) \geq 0, \text{ all } k, t;
 \end{aligned}$$

Nonanticipativity:

$x(k, t, \sigma') - x(k, t, \sigma) = 0$ if $\sigma', \sigma \in S^t_i$ for all t, i, σ', σ
 This says decision cannot depend on future.

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DATA and SOLUTIONS

- **ASSUME:**
 - $Y=15$ years
 - $G=\$80,000$
 - $T=3$ (5 year intervals)
 - $k=2$ (stock/bonds)
- **Returns (5 year):**
 - **Scenario A:** $r(\text{stock}) = 1.25$ $r(\text{bonds}) = 1.14$
 - **Scenario B:** $r(\text{stock}) = 1.06$ $r(\text{bonds}) = 1.12$
- **Solution:**

PERIOD	SCENARIO	STOCK	BONDS
1	1-8	41.5	13.5
2	1-4	65.1	2.17
2	5-8	36.7	22.4
3	1-2	83.8	0
3	3-4	0	71.4
3	5-6	0	71.4
3	7-8	64.0	0

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GENERAL MULTISTAGE MODEL

- FORMULATION:

$$\begin{aligned} \text{MIN} \quad & E [\sum_{t=1}^T f_t(x_t, x_{t+1})] \\ \text{s.t.} \quad & x_t \in X_t \\ & x_t \text{ nonanticipative} \\ & P[h_t(x_t, x_{t+1}) \leq 0] \geq \alpha \text{ (chance constraint)} \end{aligned}$$

- EXAMPLES:

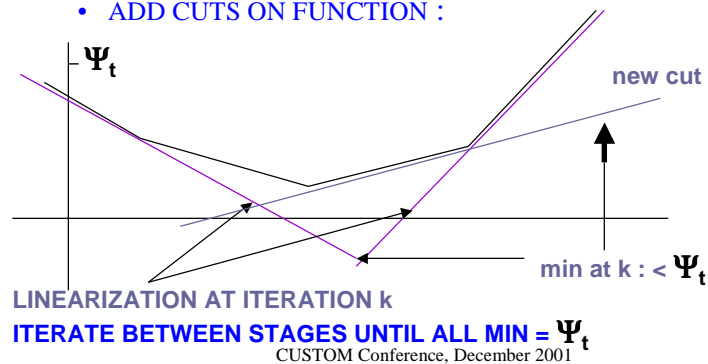
- Vehicle Allocation:** Linear functions, continuous or integer variables
- Capacity:** Linear plus integer variables
- Financial Planning:** Nonlinear objective, continuous variables

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DECOMPOSITION METHODS

- BENDERS IDEA
 - FORM AN OUTER LINEARIZATION OF Ψ_t - VALUE FUNCTION AT STAGE t
 - ADD CUTS ON FUNCTION :



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DECOMPOSITION IMPLEMENTATION

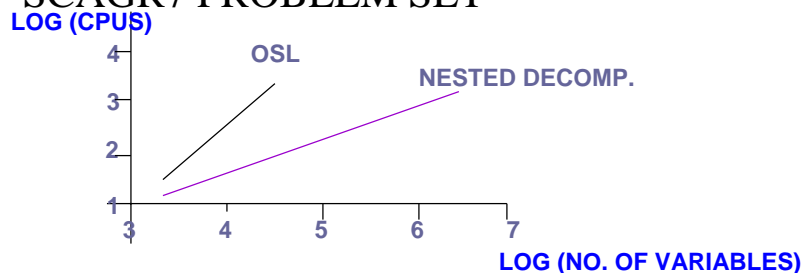
- **NESTED DECOMPOSITION**
 - **LINEARIZATION OF VALUE FUNCTION AT EACH STAGE**
 - **DECISIONS ON WHICH STAGE TO SOLVE, WHICH PROBLEMS AT EACH STAGE**
- **LINEAR PROGRAMMING SOLUTIONS**
 - **USED OSL/CPLEX FOR LINEAR SUBPROBLEMS**
 - **USE MINOS FOR NONLINEAR PROBLEMS**
- **PARALLEL IMPLEMENTATION**

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RESULTS

- **SCAGR7 PROBLEM SET**



PARALLEL: 60-80% EFFICIENCY IN SPEEDUP

OTHER PROBLEMS: SIMILAR RESULTS

- **ONLY < ORDER OF MAGNITUDE SPEEDUP WITH STORM**
- **TWO-STAGES - LITTLE COMMONALITY IN SUBPROBLEMS**
- **STILL ABLE TO SOLVE ORDER OF MAGNITUDE LARGER PROBLEMS**

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View Ahead

- New Trends
 - Methods for integer variables
 - Power system implementations
 - Vehicle routing
 - Integrating simulation
 - Sampling with optimization
 - On-line optimization
 - Low-discrepancy methods

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More Trends

- Modeling languages
 - Ability to build stochastic programs directly
 - Integrating across systems
- Using application structure
 - Separation of problem (dimension reduction)
 - Network properties
 - Generalized versions of convexity

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Summary

- Increasing application base
- Value for solving the stochastic problem
- Efficient implementations
- Opportunities for new results