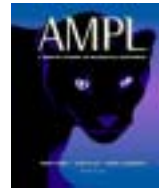


# **Numerical Issues and Influences in the Design of Algebraic Modeling Languages for Optimization**



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## **Abstract**

The idea of a modeling language is to describe mathematical problems in a symbolic form that is familiar to people, but that can be processed by computer systems. In particular the concept of an algebraic modeling language, based on objective and constraint expressions in terms of decision variables, has proved to be valuable for a broad range of optimization and related problems.

One modeling language can work with numerous solvers, each of which implements one or more optimization algorithms. The separation of model specification from solver execution is thus a key tenet of modeling language design. Nevertheless, several issues in numerical analysis that are critical to solvers are also important in implementations of modeling languages. So-called presolve procedures, which tighten bounds with the aim of eliminating some variables and constraints, are numerical algorithms that require carefully chosen tolerances and can benefit from directed roundings. Correctly rounded binary-decimal conversion is valuable in portably conveying problem instances and in debugging. Further rounding options offer tradeoffs between accuracy, convenience, and readability in displaying numerical data.

Modeling languages can also strongly influence the development of solvers. Most notably, for smooth nonlinear optimization, the ability to provide numerically computed, exact first and second derivatives has made modeling languages a valuable tool in solver development. The generality of modeling languages has also encouraged the development of more general solvers, such as for optimization problems with equilibrium constraints.

This presentation draws from our experience in developing the AMPL modeling language to provide examples in all of the above areas. We conclude by describing possibilities for future work that would have a significant numerical aspect.

## Outline

### ***Rounding and conversion***

Displayed vs. actual values  
Correctly rounded conversions

### ***Presolving***

Fixed variables, redundant constraints  
Infeasible constraints

### ***Influence on solvers***

Second derivatives  $\leftrightarrow$  IP solvers  
Complementarity problems  $\leftrightarrow$  MPECs

### ***Future influences***

Quadratic expressions  
Matrix functions and constraints  
Nonlinear expressions as *input* to solvers

## **A Brief Introduction to AMPL: The McDonald's Diet Problem**

### ***Foods:***

QP Quarter Pounder  
FR Fries, small  
MD McLean Deluxe  
SM Sausage McMuffin  
BM Big Mac  
1M 1% Lowfat Milk  
FF Filet-O-Fish  
OJ Orange Juice  
MC McGrilled Chicken

### ***Nutrients:***

Prot Protein  
Iron Iron  
VitA Vitamin A  
Cals Calories  
VitC Vitamin C  
Carb Carbohydrates  
Calc Calcium

## McDonald's Diet Problem Data

	QP	MD	BM	FF	MC	FR	SM	1M	OJ	
<b>Cost</b>	<b>1.8</b>	<b>2.2</b>	<b>1.8</b>	<b>1.4</b>	<b>2.3</b>	<b>0.8</b>	<b>1.3</b>	<b>0.6</b>	<b>0.7</b>	<b>Need:</b>
<b>Protein</b>	28	24	25	14	31	3	15	9	1	<b>55</b>
<b>Vitamin A</b>	15	15	6	2	8	0	4	10	2	<b>100</b>
<b>Vitamin C</b>	6	10	2	0	15	15	0	4	120	<b>100</b>
<b>Calcium</b>	30	20	25	15	15	0	20	30	2	<b>100</b>
<b>Iron</b>	20	20	20	10	8	2	15	0	2	<b>100</b>
<b>Calories</b>	510	370	500	370	400	220	345	110	80	<b>2000</b>
<b>Carbo</b>	34	35	42	38	42	26	27	12	20	<b>350</b>

## Formulation: Too General

*Minimize*  $cx$

*Subject to*  $Ax = b$

$x \geq 0$

## Formulation: Too Specific

$$\begin{array}{l}
 \text{Minimize} \quad 1.84 x_{QP} + 2.19 x_{MD} + 1.84 x_{BM} + 1.44 x_{FF} + 2.29 x_{MC} + 0.77 x_{FR} + 1.29 x_{SM} + 0.60 x_{IM} + 0.72 x_{OI} \\
 \text{Subject to} \quad 28 x_{QP} + 24 x_{MD} + 25 x_{BM} + 14 x_{FF} + 31 x_{MC} + 3 x_{FR} + 15 x_{SM} + 9 x_{IM} + 1 x_{OI} \geq 55 \\
 \quad 15 x_{QP} + 15 x_{MD} + 6 x_{BM} + 2 x_{FF} + 8 x_{MC} + 0 x_{FR} + 4 x_{SM} + 10 x_{IM} + 2 x_{OI} \geq 100 \\
 \quad 6 x_{QP} + 10 x_{MD} + 2 x_{BM} + 0 x_{FF} + 15 x_{MC} + 15 x_{FR} + 0 x_{SM} + 4 x_{IM} + 120 x_{OI} \geq 100 \\
 \quad 30 x_{QP} + 20 x_{MD} + 25 x_{BM} + 15 x_{FF} + 15 x_{MC} + 0 x_{FR} + 20 x_{SM} + 30 x_{IM} + 2 x_{OI} \geq 100 \\
 \quad 20 x_{QP} + 20 x_{MD} + 20 x_{BM} + 10 x_{FF} + 8 x_{MC} + 2 x_{FR} + 15 x_{SM} + 0 x_{IM} + 2 x_{OI} \geq 100 \\
 \quad 510 x_{QP} + 370 x_{MD} + 500 x_{BM} + 370 x_{FF} + 400 x_{MC} + 220 x_{FR} + 345 x_{SM} + 110 x_{IM} + 80 x_{OI} \geq 2000 \\
 \quad 34 x_{QP} + 35 x_{MD} + 42 x_{BM} + 38 x_{FF} + 42 x_{MC} + 26 x_{FR} + 27 x_{SM} + 12 x_{IM} + 20 x_{OI} \geq 350
 \end{array}$$

## Formulation: Algebraic Model

**Given**  $\mathcal{F}$ , a set of foods  
 $\mathcal{N}$ , a set of nutrients

**and**  $a_{ij} \geq 0$ , the units of nutrient  $i$  in one serving of food  $j$ ,  
for each  $i \in \mathcal{N}$  and  $j \in \mathcal{F}$

$b_i > 0$ , the units of nutrient  $i$  required, for each  $i \in \mathcal{N}$

$c_j > 0$ , the cost per serving of food  $j$ , for each  $j \in \mathcal{F}$

**Define**  $x_j \geq 0$ , the number of servings of food  $j$  to be purchased, for each  $j \in \mathcal{F}$

**Minimize**  $\sum_{j \in \mathcal{F}} c_j x_j$

**Subject to**  $\sum_{j \in \mathcal{F}} a_{ij} x_j \geq b_i$ , for each  $i \in \mathcal{N}$

## Algebraic Model in AMPL

```

set NUTR; # nutrients
set FOOD; # foods

param amt {NUTR,FOOD} >= 0; # amount of nutrient in each food
param nutrLow {NUTR} >= 0; # lower bound on nutrients in diet
param cost {FOOD} >= 0; # cost of foods

var Buy {FOOD} >= 0 integer; # amounts of foods to be purchased

minimize TotalCost: sum {j in FOOD} cost[j] * Buy[j];

subject to Need {i in NUTR}:
    sum {j in FOOD} amt[i,j] * Buy[j] >= nutrLow[i];

```

## Data for the AMPL Model

```

param: FOOD:          cost :=
    "Quarter Pounder"  1.84   "Fries, small"          .77
    "McLean Deluxe"   2.19   "Sausage McMuffin"     1.29
    "Big Mac"          1.84   "1% Lowfat Milk"       .60
    "Filet-O-Fish"    1.44   "Orange Juice"         .72
    "McGrilled Chicken" 2.29 ;

param: NUTR: nutrLow :=
    Prot 55  VitA 100  VitC 100
    Calc 100  Iron 100  Cals 2000  Carb 350 ;

param amt (tr):      Cals  Carb  Prot  VitA  VitC  Calc  Iron :=
    "Quarter Pounder"  510  34  28  15  6  30  20
    "McLean Deluxe"   370  35  24  15  10  20  20
    "Big Mac"          500  42  25  6  2  25  20
    "Filet-O-Fish"    370  38  14  2  0  15  10
    "McGrilled Chicken" 400  42  31  8  15  15  8
    "Fries, small"    220  26  3  0  15  0  2
    "Sausage McMuffin" 345  27  15  4  0  20  15
    "1% Lowfat Milk"  110  12  9  10  4  30  0
    "Orange Juice"    80  20  1  2  120  2  2 ;

```

## Continuous-Variable Solution

```
ampl: model mcdiet1.mod;
ampl: data mcdiet1.dat;

ampl: solve;

MINOS 5.5: ignoring integrality of 9 variables
MINOS 5.5: optimal solution found.
7 iterations, objective 14.8557377

ampl: display Buy;

Buy [*] :=
    1% Lowfat Milk    3.42213
           Big Mac    0
           Filet-O-Fish 0
           Fries, small 6.14754
    McGrilled Chicken 0
           McLean Deluxe 0
           Orange Juice 0
           Quarter Pounder 4.38525
           Sausage McMuffin 0
```

## Integer-Variable Solution

```
ampl: option solver cplex;

ampl: solve;

CPLEX 8.1.0: optimal integer solution; objective 15.05
27 MIP simplex iterations
15 branch-and-bound nodes

ampl: display Buy;

Buy [*] :=
    1% Lowfat Milk    4
           Big Mac    0
           Filet-O-Fish 1
           Fries, small 5
    McGrilled Chicken 0
           McLean Deluxe 0
           Orange Juice 0
           Quarter Pounder 4
           Sausage McMuffin 0
```

## Same for 63 Foods, 12 Nutrients

```
ampl: reset data;
ampl: data mcdiet2.dat;

ampl: option solver minos;
ampl: solve;
MINOS 5.5: ignoring integrality of 63 variables
MINOS 5.5: optimal solution found.
16 iterations, objective -1.786806582e-14

ampl: option omit_zero_rows 1;
ampl: display Buy;
Buy [*] :=
           Bacon Bits    55
           Barbeque Sauce 50
           Hot Mustard Sauce 50
```

## Revised Algebraic Model in AMPL

```
set NUTR ordered;
set FOOD ordered;

param cost {FOOD} >= 0;
param f_min {FOOD} >= 0, default 0;
param f_max {j in FOOD} >= f_min[j], default Infinity;

param n_min {NUTR} >= 0, default 0;
param n_max {i in NUTR} >= n_min[i], default Infinity;

param amt {NUTR,FOOD} >= 0

var Buy {j in FOOD} integer >= f_min[j], <= f_max[j];

minimize Total_Cost: sum {j in FOOD} cost[j] * Buy[j];
minimize Nutr_Amt {i in NUTR}: sum {j in FOOD} amt[i,j] * Buy[j];

subject to Diet {i in NUTR}:
  n_min[i] <= sum {j in FOOD} amt[i,j] * Buy[j] <= n_max[i];
```

## Revised Algebraic Model in AMPL (*cont'd*)

```
subject to McNuggetsSauces:
    Buy["Hot Mustard Sauce"] + Buy["Barbeque Sauce"] +
    Buy["Sweet 'N Sour Sauce"] + Buy["Honey"]

    <= 2 * Buy["Chicken McNuggets (6 pcs)"] +
    3 * Buy["Chicken McNuggets (9 pcs)"] +
    6 * Buy["Chicken McNuggets (20 pcs)"];

subject to SaladToppings:
    Buy["Croutons"] + Buy["Bacon Bits"]

    <= Buy["Chef Salad"] + Buy["Chunky Chicken Salad"] +
    Buy["Garden Salad"] + Buy["Side Salad"];

subject to SaladDressings:
    Buy["Bleu Cheese Dressing"] + Buy["Ranch Dressing"] +
    Buy["1000 Island Dressing"] + Buy["Lite Vinaigrette Dressing"] +
    Buy["French Rdc'd Cal Dressing"]

    <= Buy["Chef Salad"] + Buy["Chunky Chicken Salad"] +
    Buy["Garden Salad"] + Buy["Side Salad"];
```

## Revised Algebraic Model in AMPL (*cont'd*)

```
subject to OneDrinkPerMeal:
    3 = Buy["Vanilla Shake"] + Buy["Chocolate Shake"] +
    Buy["Strawberry Shake"] +

    Buy["1% Lowfat Milk"] + Buy["Orange Juice"] +

    Buy["Coca-Cola (small)"] + Buy["Coca-Cola (medium)"] +
    Buy["Coca-Cola (large)"] +

    Buy["Diet Coke (small)"] + Buy["Diet Coke (medium)"] +
    Buy["Diet Coke (large)"] +

    Buy["Sprite (small)"] + Buy["Sprite (medium)"] +
    Buy["Sprite (large)"] +

    Buy["H-C Orange Drink (small)"] +
    Buy["H-C Orange Drink (medium)"] +
    Buy["H-C Orange Drink (large)"];

subject to FatCaloriesLimit:
    sum {j in FOOD} amt["CalFat",j] * Buy[j]
    <= 0.3 * sum {j in FOOD} amt["Cal",j] * Buy[j];
```



## Revised Solution (at most 2 of every food)

```
ampl: reset;

ampl: model mcdiet2.mod
ampl: data mcdiet2all.dat;

ampl: option solver cplex;
ampl: solve;

CPLEX 8.1.0: optimal integer solution; objective 8.86
511 MIP simplex iterations
325 branch-and-bound nodes

ampl: display Buy;

Buy [*] :=
           Cheerios  1
           Cheeseburger 2
'H-C Orange Drink (large)' 1
           Hamburger 2
           'Orange Juice' 1
'Raspberry Danish' 1
           'Side Salad' 1
'Strawberry Shake' 1
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 17

## Essential Modeling Language Features

### *Sets and indexing*

- Simple sets
- Compound sets
- Computed sets

### *Variables, objectives and constraints*

- Linear, piecewise-linear
- Nonlinear
- Integer

### *and much more . . .*

- Express problems in the various ways that people do**
- Support a broad variety of modeling situations
- Drive varied solvers

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## **Modeling Language Features** (*cont'd*)

### ***Programming iterative schemes***

- Loops over sets, **if-then-else** tests
- Switching between subproblems
- Debugging

### ***Representing other types of models***

- Complementarity problems
- General combinatorial problems (*to come*)
- Stochastic programs (*to come*)

### ***Communicating with other systems***

- Relational database access
- Internet optimization services
- Solver-specific directives, results & diagnostic information

## **Commercial Modeling Languages**

***AIMMS*** [www.aimms.com](http://www.aimms.com)

***AMPL*** [www.ampl.com](http://www.ampl.com)

***GAMS*** [www.gams.com](http://www.gams.com)

***LINGO*** [www.lindo.com](http://www.lindo.com)

***MPL*** [www.maximal-usa.com](http://www.maximal-usa.com)

***OPL*** [www.ilog.com/products/oplstudio/](http://www.ilog.com/products/oplstudio/)

## Airline Fleet Assignment

```
set FLEETS;  
param fleet_size {FLEETS} >= 0;  
  
set CITIES;  
set TIMES circular;  
  
set FLEET_LEGS within  
  {f in FLEETS, c1 in CITIES, t1 in TIMES,  
   c2 in CITIES, t2 in TIMES: c1 <> c2 and t1 <> t2};  
  # (f,c1,t1,c2,t2) represents the availability of fleet f  
  # to cover the leg that leaves c1 at t1 and  
  # whose arrival time plus turnaround time at c2 is t2  
param leg_cost {FLEET_LEGS} >= 0;
```

## Computed Sets

```
set LEGS := setof {(f,c1,t1,c2,t2) in FLEET_LEGS} (c1,t1,c2,t2);  
  # the set of all legs that can be covered by some fleet  
  
set SERV_CITIES {f in FLEETS} :=  
  union {(f,c1,c2,t1,t2) in FLEET_LEGS} {c1,c2};  
  
  # for each fleet, the set of cities that it serves  
  
set OP_TIMES {f in FLEETS, c in SERV_CITIES[f]} circular by TIMES :=  
  setof {(f,c,c2,t1,t2) in FLEET_LEGS} t1 union  
  setof {(f,c1,c,t1,t2) in FLEET_LEGS} t2;  
  
  # for each fleet and city served by that fleet,  
  # the set of active arrival & departure times at that city,  
  # with arrival time padded for turn requirements
```

## Underlying Network Model

```
minimize Total_Cost;

node Balance {f in FLEETS, c in SERV_CITIES[f], OP_TIMES[f,c]};
    # for each fleet and city served by that fleet,
    # a node for each possible time

arc Fly {(f,c1,t1,c2,t2) in FLEET_LEGS} >= 0, <= 1,
    from Balance[f,c1,t1], to Balance[f,c2,t2],
    obj Total_Cost leg_cost[f,c1,t1,c2,t2];
    # arcs for fleet/flight assignments

arc Sit {f in FLEETS, c in SERV_CITIES[f], t in OP_TIMES[f,c]} >= 0,
    from Balance[f,c,t], to Balance[f,c,next(t)];
    # arcs for planes on the ground
```

## Service and Fleet-Size Constraints

```
subj to Service {(c1,t1,c2,t2) in LEGS}:
    sum {(f,c1,t1,c2,t2) in FLEET_LEGS} Fly[f,c1,t1,c2,t2] = 1;
    # each leg must be served by some fleet

subj to FleetSize {f in FLEETS}:
    sum {(f,c1,t1,c2,t2) in FLEET_LEGS:
        ord(t2,TIMES) < ord(t1,TIMES)} Fly[f,c1,t1,c2,t2] +
    sum {c in SERV_CITIES[f]} Sit[f,c,last(OP_TIMES[f,c])] <= fleet_size[f];
    # number of planes used is the number in the air at the
    # last time (arriving "earlier" than they leave)
    # plus the number on the ground at the last time in each city
```

## Rounding and Conversion

### *Rounding*

- Display of zeros
- Number of displayed digits
- Number of actual digits

### *Conversion*

- Correctly rounded binary  $\leftrightarrow$  decimal conversion
- “Maximum” precision

## Display “epsilon”

### production-transportation model

```
var Make {ORIG,PROD} >= 0;      # tons produced at origins
var Trans {ORIG,DEST,PROD} >= 0; # tons shipped

minimize Total_Cost:
  sum {i in ORIG, p in PROD} make_cost[i,p] * Make[i,p] +
  sum {i in ORIG, j in DEST, p in PROD} trans_cost[i,j,p] * Trans[i,j,p];

subject to Time {i in ORIG}:
  sum {p in PROD} (1/rate[i,p]) * Make[i,p] <= avail[i];

subject to Supply {i in ORIG, p in PROD}:
  sum {j in DEST} Trans[i,j,p] = Make[i,p];

subject to Demand {j in DEST, p in PROD}:
  sum {i in ORIG} Trans[i,j,p] = demand[j,p];
```

## Display “epsilon” (cont’d)

```
ampl: model steelP.mod;
ampl: data steelP.dat;
ampl: solve;
MINOS 5.5: optimal solution found.
27 iterations, objective 1392175
ampl: display Make;
Make [*,*]
:      bands      coils      plate      :=
CLEV   1.91561e-14  1950      3.40429e-14
GARY   1125         1750      300
PITT   775         500       500
;
ampl: option display_eps 1e-10;
ampl: display Make;
Make [*,*]
:      bands      coils      plate :=
CLEV   0          1950      0
GARY   1125       1750      300
PITT   775       500       500
;
```

## Display Precision

economic equilibrium model with price-sensitive demands

```
set PROD; # products
set ACT; # activities
param cost {ACT} > 0; # cost per unit of each activity
param io {PROD,ACT} >= 0; # units of each product from
# 1 unit of each activity
param demzero {PROD} > 0; # intercept and slope of the demand
param demrate {PROD} >= 0; # as a function of price
var Price {i in PROD};
var Level {j in ACT};
subject to Pri_Cmpl {i in PROD}:
    Price[i] >= 0 complements
    sum {j in ACT} io[i,j] * Level[j] >= demzero[i] - demrate[i] * Price[i];
subject to Lev_Cmpl {j in ACT}:
    Level[j] >= 0 complements
    sum {i in PROD} Price[i] * io[i,j] <= cost[j];
```

## Display Precision (*cont'd*)

```
ampl: model econnl.mod;
ampl: data econnl.dat;
ampl: solve;

Job has been submitted to Kestrel
Kestrel/NEOS Job number   : 273481
Kestrel/NEOS Job password : ymDKgiDn
Check the following URL for progress report :
.....
Path v4.5: Solution found.
13 iterations (5 for crash); 10 pivots.
20 function, 14 gradient evaluations.

ampl: option omit_zero_rows 1;
ampl: display Price;

Price [*] :=
AA1  16.7051
AC1  5.44585
BC1  48.909
BC2  8.90899
;
```

## Display Precision (*cont'd*)

```
ampl: option display_precision 4;
ampl: display Level;

Level [*] :=
Pla  450.7
P3   190.1
P3c  1789
;

ampl: option display_precision 9;
ampl: display Level;

Level [*] :=
Pla  450.681489
P3   190.123755
P3c  1789.33403
;

ampl: option display_precision 0; # "maximum" precision
ampl: display Level;

Level [*] :=
Pla  450.68148928230426
P3   190.1237550901998
P3c  1789.3340267897368
;
```

## Display Rounding

```
AMPL: display Price;
Price [*] :=
AA1 16.7051
AC1 5.44585
BC1 48.909
BC2 8.90899
;
AMPL: option display_round 2;
AMPL: display Price;
Price [*] :=
AA1 16.71
AC1 5.45
BC1 48.91
BC2 8.91
;
AMPL: option display_round 0;
AMPL: display Price;
Price [*] :=
AA1 17
AC1 5
BC1 49
BC2 9
;
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 31

## Maximum Precision

### *Correctly rounded decimal-to-binary conversion*

Binary value “closest” to a given decimal number,  
for given binary representation and rounding sense

Clinger (1990) uses IEEE double-extended arithmetic

Gay (1990) adapts to use double-precision arithmetic

### *Correctly rounded binary-to-decimal conversion*

**Shortest decimal number** that yields a given binary number  
when correctly rounded back to the given precision

Variants for given number of digits or digits after decimal point

Proposed by Steele and White (1990), speeded by Gay (1990)

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## Maximum Precision: Efficiency

	(1)	(2)	(3)	(4)	(5)
1.23	31	29	109	21	77
1.23e+20	33	31	137	25	71
1.23e-20	33	31	195	26	77
1.23456789	30	37	261	17	78
1.23456589e+20	32	38	285	22	85
1.23456789e-20	32	39	415	22	76
1234565	47	53	36	26	68
1.234565	131	268	210	17	76
1.234565e+20	157	285	237	22	74
1.234565e-20	208	341	335	23	80

High-precision  
integer arithmetic

- (1) Gay (1990), 6 places
- (2) Steele and White (1990), 6 places
- (3) Gay (1990), **maximum precision**
- (4) C library routine `ecvt`, 6 places
- (5) C library function `sprintf("%g")`, 6 places

## Maximum Precision: Uses

### *Set membership*

Different numerical set objects always display differently

### *Communication with solvers*

Equivalent text and binary forms are available

### *Debugging results*

Exact results can be viewed

Unexpected rounding anomalies can be diagnosed . . .

## Solution Precision

scheduling given demands and acceptable schedules

```
set SHIFTS;           # shifts
param Nsched;        # number of schedules;
set SCHEDS = 1..Nsched; # set of schedules
set SHIFT_LIST {SCHEDS} within SHIFTS; # shifts worked in each schedule
param required {SHIFTS} >= 0;           # workers needed on each shift

minimize Total_Cost;

subject to Shift_Needs {i in SHIFTS}: to_come >= required[i];

var Work {j in SCHEDS} >= 0,
    obj Total_Cost 1, coeff {i in SHIFT_LIST[j]} Shift_Needs[i] 1;
```

```
set SHIFTS := Mon1 Tue1 Wed1 Thu1 Fri1 Sat1
            Mon2 Tue2 Wed2 Thu2 Fri2 Sat2
            Mon3 Tue3 Wed3 Thu3 Fri3 ;

param Nsched := 126 ;

set SHIFT_LIST[1] := Mon1 Tue1 Wed1 Thu1 Fri1 ;
set SHIFT_LIST[2] := Mon1 Tue1 Wed1 Thu1 Fri2 ;
set SHIFT_LIST[3] := Mon1 Tue1 Wed1 Thu1 Fri3 ; .....
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 35

## Solution Precision (cont'd)

```
ampl: model sched.mod;
ampl: data sched.dat;
ampl: solve;
MINOS 5.5: optimal solution found.
19 iterations, objective 265.6
ampl: option omit_zero_rows 1;
ampl: option display_eps .000001;
ampl: display Work;
Work [*] :=
10 28.8    73 28
18  7.6    87 14.4
24  6.8   106 23.2
30 14.4   109 14.4
35  6.8   113 14.4
66 35.6   123 35.6
71 35.6
;
ampl: display sum {j in SCHEDS} ceil(Work[j]); # objective rounded up
sum{j in SCHEDS} ceil(Work[j]) = 273
ampl: display 29+8+7+15+7+36+36+28+15+24+15+15+36;
29 + 8 + 7 + 15 + 7 + 36 + 36 + 28 + 15 + 24 + 15 + 15 + 36 = 271
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 36

## Solution Precision (*cont'd*)

```
ampl: model sched.mod;
ampl: data sched.dat;
ampl: solve;
MINOS 5.5: optimal solution found.
19 iterations, objective 265.6
ampl: option display_precision 0;
ampl: display Work;
Work [*] :=
10 28.799999999999997      73 28.000000000000018
18  7.599999999999998      87 14.399999999999995
24  6.799999999999999      95 -5.876671973951407e-15
30 14.400000000000001      106 23.200000000000006
35  6.799999999999995      108  4.685288280240683e-16
55 -4.939614313857677e-15  109 14.4
66 35.6                    113 14.4
71 35.599999999999994     123 35.599999999999999
;
```

## Solution Precision (*cont'd*)

```
ampl: model sched.mod;
ampl: data sched.dat;
ampl: option solution_round 6;
ampl: solve;
MINOS 5.5: optimal solution found.
19 iterations, objective 265.6
ampl: display Work;
Work [*] :=
10 28.8      73 28
18  7.6      87 14.4
24  6.8      106 23.2
30 14.4      109 14.4
35  6.8      113 14.4
66 35.6      123 35.6
71 35.6
;
ampl: display sum {j in SCHEDS} ceil(Work[j]);
sum{j in SCHEDS} ceil(Work[j]) = 271
```

## Other Precision and Rounding Options

```
AMPL: option *precision*;  
option MD_precision 0;  
option csvdisplay_precision 0;  
option display_precision 6;  
option expand_precision 6;  
option objective_precision 10;  
option output_precision 0;  
option print_precision 0;  
option solution_precision '';  
  
AMPL: option *round*;  
option csvdisplay_round '';  
option display_round '';  
option expand_round '';  
option print_round '';  
option solution_round '';
```

## Presolve

### *Motivation*

Treat all simple bounds the same, however declared

```
> var Sell {p in PROD, t in 1..T} >= 0, <= market[p,t];  
> var Sell {PROD,1..T} >= 0;  
    subj to MLim {p in PROD, t in 1..T}: Sell[p,t] <= market[p,t];
```

Remove fixed variables, redundant constraints

### *Idea*

Substitute bounds into constraints to deduce tighter bounds

### *Based on*

A.L. Brearly, G. Mitra and H.P. Williams, “Analysis of Mathematical Programming Problems Prior to Applying the Simplex Algorithm.”  
*Mathematical Programming* 8 (1975) 54–83.

## Presolve 1: Variable Defined as Fixed

### multi-period production planning

```
AMPL: model steelT.mod;
AMPL: data steelT.dat;
AMPL: option show_stats 1;
AMPL: solve;
Presolve eliminates 2 constraints and 2 variables.
Adjusted problem:
24 variables, all linear
12 constraints, all linear; 38 nonzeros
1 linear objective; 24 nonzeros.
MINOS 5.5: optimal solution found.
15 iterations, objective 515033

AMPL: print {j in 1.._nvars: _var[j].status = "pre"}: _varname[j];
Inv['bands',0]
Inv['coils',0]
AMPL: print {i in 1.._ncons: _con[i].status = "pre"}: _conname[i];
Init_Inv['bands']
Init_Inv['coils']

AMPL: show Init_Inv;
subject to Init_Inv{p in PROD} : Inv[p,0] == inv0[p];
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 41

## Presolve 2: Redundancy Implied by Original Bounds

### diet cost minimization

```
AMPL: model dietu.mod;
AMPL: data dietu.dat;
AMPL: solve;
Presolve eliminates 3 constraints.
Adjusted problem:
8 variables, all linear
5 constraints, all linear; 39 nonzeros
1 linear objective; 8 nonzeros.
MINOS 5.5: optimal solution found.
5 iterations, objective 74.27382022

AMPL: print {i in 1.._ncons: _con[i].status = "pre"}: _conname[i];
Diet_Min['B1']
Diet_Min['B2']
Diet_Max['A']
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 42

## Presolve 2 (cont'd)

```
AMPL: show Diet_Min;
subj to Diet_Min{i in MINREQ}: sum{j in FOOD} amt[i,j]*Buy[j] >= n_min[i];

AMPL: show Diet_Max;
subj to Diet_Max{i in MAXREQ}: sum{j in FOOD} amt[i,j]*Buy[j] <= n_max[i];

AMPL: show Buy;
var Buy{j in FOOD} >= f_min[j], <= f_max[j];

AMPL: display n_min;
n_min [*] :=
  A    700
  B1    0
  B2    0
  C    700
  CAL  16000
;

AMPL: display {i in MAXREQ} (n_max[i], sum {j in FOOD} amt[i,j]*f_max[j]);
: n_max[i] sum{j in FOOD} amt[i,j]*f_max[j] :=
A    20000      2860
CAL  24000      34700
NA   50000      91450
;
```

## Presolve 3: Redundancy Implied by Inferred Bounds multi-commodity transportation

```
AMPL: model multi.mod;
AMPL: data multi.dat;
AMPL: solve;

Presolve eliminates 7 constraints and 3 variables.
Adjusted problem:
60 variables, all linear
44 constraints, all linear; 165 nonzeros
1 linear objective; 60 nonzeros.
MINOS 5.5: optimal solution found.
41 iterations, objective 199500

AMPL: print {j in 1..nvars: _var.status[j] = "pre"}: _varname[j];
Trans['GARY','LAN','plate']
Trans['CLEV','LAN','plate']
Trans['PITT','LAN','plate']
AMPL: print {i in 1..ncons: _con[i].status = "pre"}: _conname[i];
Demand['LAN','plate']
Multi['GARY','LAN']
Multi['GARY','WIN']
Multi['CLEV','LAN']
Multi['CLEV','WIN']
Multi['PITT','LAN']
Multi['PITT','WIN']
```

## Presolve 3 (cont'd)

```
AMPL: expand Demand['LAN','plate'];
subject to Demand['LAN','plate']:
    Trans['GARY','LAN','plate'] + Trans['CLEV','LAN','plate'] +
    Trans['PITT','LAN','plate'] = 0;

AMPL: show Multi;
subject to Multi {i in ORIG, j in DEST}:
    sum {p in PROD} Trans[i,j,p] <= limit[i,j];

AMPL: display {i in ORIG, j in DEST}
AMPL? sum {p in PROD} Trans[i,j,p].ub - limit[i,j];
sum{p in PROD} (Trans[i,j,p].ub) - limit[i,j] [*,*] (tr)
:      CLEV      GARY      PITT      :=
DET   Infinity   Infinity   Infinity
FRA   Infinity   Infinity   Infinity
FRE   Infinity   Infinity   Infinity
LAF   Infinity   Infinity   Infinity
LAN   Infinity   Infinity   Infinity
STL   Infinity   Infinity   Infinity
WIN   Infinity   Infinity   Infinity
;
```

## Presolve 3 (cont'd)

```
AMPL: display {i in ORIG, j in DEST}
AMPL? sum {p in PROD} Trans[i,j,p].ub2 - limit[i,j];
sum{p in PROD} (Trans[i,j,p].ub2) - limit[i,j] [*,*] (tr)
:      CLEV      GARY      PITT      :=
DET   400        400        400
FRA   275        275        275
FRE   325        325        325
LAF   375        325        375
LAN   -125       -125       -125
STL   825        600        825
WIN   -250       -250       -250
;
```

```
AMPL: show Supply;
subject to Supply {i in ORIG, p in PROD}:
    sum {j in DEST} Trans[i,j,p] == supply[i,p];
AMPL: show Demand;
subject to Demand {j in DEST, p in PROD}:
    sum {i in ORIG} Trans[i,j,p] == demand[j,p];
```

## Presolve 4: Infeasibility

time-constrained production

```
set PROD; # products
param rate {PROD} > 0; # produced tons per hour
param avail >= 0; # hours available in week
param profit {PROD}; # profit per ton
param commit {PROD} >= 0; # lower limit on tons sold in week
param market {PROD} >= 0; # upper limit on tons sold in week

var Make {p in PROD} >= commit[p], <= market[p];

maximize Total_Profit: sum {p in PROD} profit[p] * Make[p];

subject to Time: sum {p in PROD} (1/rate[p]) * Make[p] <= avail;
```

```
ampl: model steel3.mod;
ampl: data steel3.dat;
ampl: let avail := 13;
ampl: solve;
presolve: constraint Time cannot hold:
        body <= 13 cannot be >= 13.2589; difference = -0.258929
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 47

## Presolve 4 (cont'd)

```
ampl: display sum {p in PROD} (1/rate[p])*Make[p].lb;
sum{p in PROD} 1/rate[p]*(Make[p].lb) = 13.2589

ampl: let avail := 13.2589;
ampl: solve;
presolve: constraint Time cannot hold:
        body <= 13.2589 cannot be >= 13.2589; difference = -2.85714e-05

ampl: let avail := 13.25895;
ampl: solve;
MINOS 5.5: optimal solution found.
0 iterations, objective 61750.10714

ampl: let avail := 13.258925;
ampl: solve;
presolve: constraint Time cannot hold:
        body <= 13.2589 cannot be >= 13.2589; difference = -3.57143e-06
Setting $presolve_eps >= 4.29e-06 might help.

ampl: option presolve_epsmax;
option presolve_epsmax 1e-5;
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 48



## Presolve 4 (cont'd)

```
ampl: let avail := 13.258925;
ampl: solve;
presolve: constraint Time cannot hold:
      body <= 13.2589 cannot be >= 13.2589; difference = -3.57143e-06
Setting $presolve_eps >= 4.29e-06 might help.

ampl: option presolve_eps;
option presolve_eps 0;

ampl: option presolve_eps 1e-5;
ampl: solve;
MINOS 5.5: optimal solution found.
0 iterations, objective 61749.98214

ampl: option solver cplex;
ampl: solve;
CPLEX 8.1.0: Bound infeasibility column 'x1'.
infeasible problem.

ampl: option cplex_options 'feasibility=5e-3';
ampl: solve;
CPLEX 8.1.0: optimal solution; objective 194828.5714
1 dual simplex iterations (0 in phase I)
```

Robert Fourer & David M. Gay, 20th Biennial Conference on Numerical Analysis, Dundee, Scotland — 24-27 June 2003 49

## Works for Big LPs, Too!

```
ampl: option show_stats 2;
ampl: model xxx1.mod;
ampl: data xxx1.dat;
ampl: solve;

Presolve eliminates 1769 constraints and 8747 variables.
"option presolve 10;" used, but "option presolve 4;" would suffice.
Adjusted problem:
19369 variables, all linear
3511 constraints, all linear; 150362 nonzeros      #      2 sec in AMPL,
1 linear objective; 19369 nonzeros.              # 1/2 sec in presolve

ampl: reset;
ampl: model xxx2.mod;
ampl: data xxx2.dat;
ampl: solve;

Presolve eliminates 32989 constraints and 54819 variables.
"option presolve 10;" used, but "option presolve 2;" would suffice.
Adjusted problem:
327710 variables, all linear
105024 constraints, all linear; 1359068 nonzeros  #      23 sec in AMPL,
1 linear objective; 317339 nonzeros.             # 4 sec in presolve
```

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## Presolve Tolerances

### *Bound fixing*

<code>presolve_fixeps</code>	0
<code>presolve_fixepsmax</code>	1e-5

### *Constraint redundancy*

<code>constraint_drop_tol</code>	0
----------------------------------	---

### *Bound infeasibility*

<code>presolve_eps</code>	0
<code>presolve_epsmax</code>	1e-5

### *Integer bound rounding*

<code>presolve_inteps</code>	1e-6
<code>presolve_intepsmax</code>	1e-5

## Presolve Computations: Directed Rounding

### *Principles*

Round lower bounds toward  $-\infty$   
Round upper bounds toward  $+\infty$

### *Practice*

Fewer false alarms in presolve  
— can leave `presolve_eps` at 0  
Not performed properly by some computers & compilers

## Influence on Solvers

### *Derivatives*

- Interaction of modeling language with nonlinear solvers
- Automatic differentiation
- Second derivatives and partial separability
- Interior-point solvers

### *Complementarity problems*

- Forms of complementarity constraints
- Solvers of square equilibrium problems and  
mathematical programs with equilibrium constraints

## How AMPL Expresses a Nonlinear Problem

### *Just write nonlinear expressions*

```
set J := 1 .. 18;  
set K := 1 .. 7;  
set PAIRS in {J,K};  
set I := 1 .. 16;  
param b {I} >= 0, default 0;  
param c {PAIRS};  
param E {PAIRS,I} integer;  
param xlb >= 0, default 0;  
  
var x {PAIRS} >= xlb, default 0.1;  
  
minimize Energy:  
    sum {(j,k) in PAIRS} x[j,k] *  
        (c[j,k] + log (x[j,k] / sum {m in J:(m,k) in PAIRS} x[m,k]));  
  
subject to H {i in I}:  
    sum {(j,k) in PAIRS} E[j,k,i] * x[j,k] = b[i];
```

## How AMPL Interacts with a Solver

### *User types . . .*

```
option solver yrslv;  
option yrslv_options "maxiter=10000";  
solve;
```

### *AMPL . . .*

Writes `at13151.nl`  
Executes “`yrslv at13151 -AMPL`”

### *YRSLV “driver” . . .*

Reads `at13151.nl`  
Gets environment variable `yrslv_options`  
Calls YRSLV routines to solve the problem  
Writes `at13151.sol`

### *AMPL . . .*

Reads `at13151.sol`

## How a Driver Interacts with a **Nonlinear** Solver

### *Reads .nl problem file*

Loads everything into *ASL data structure*  
Copies linear coefficients, bounds, etc. to solver’s arrays  
Sets directives indicated by `_options` string

### *Runs algorithm*

Uses *ASL data structure*  
to compute nonlinear expression and derivative values

### *Writes .sol solution file*

Generates result message  
Writes values of variables  
Writes other solution values, as appropriate

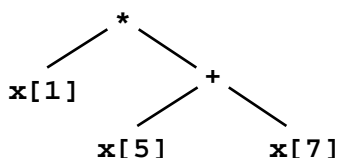
## How the .nl File Represents a Nonlinear Problem

### *File contents*

- Numbers of variables, constraints,  
integer variables, nonlinear constraints, etc.
- Coefficient lists for linear part
- Expression tree for nonlinear part plus sparsity pattern of derivatives

### *Expression tree nodes*

- Variables, constants
- Binary, unary operators
- Summations
- Function calls
- Piecewise-linear terms
- If-then-else terms



$$* \ x[1] \ + \ x[5] \ x[7]$$

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## “Backward” Automatic Differentiation

### *Computations*

- Forward sweep: compute  $\phi(x)$ ,  
save info on  $\partial f(x)/\partial o$  for each operation  $o$
- Backward sweep: recur to compute  $\nabla f(x)$

### *Complexity*

- Small multiple of time for  $f(x)$  alone
- Potentially large multiple of space

### *Advantages*

- More accurate, efficient than finite differencing
- $O(n)$  vs.  $O(n^2)$  for symbolic differentiation or forward AD
- Correct results for nondifferentiable functions  
(min, max, if-then-else, piecewise-linear)

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## 2nd Derivatives

### **Hessian-vector products: $\nabla^2 f(x) v$**

Apply backward AD to compute gradients of  $v^T \nabla f(x)$

Equivalently, compute  $\nabla_x (df(x + \tau v) / d\tau) |_{\tau=0}$

### **General case**

$\nabla^2 f(x) e_j$  for each  $j = 1, \dots, n$

### **Partially separable case**

$f(x) = \sum_{t=1}^q f_t(U_t x)$  where  $U_t$  is  $m_t \times n$ ,  $m \gg n$

$\nabla f(x) = \sum_{t=1}^q U_t^T \nabla f_t(U_t x)$

$\nabla^2 f(x) = \sum_{t=1}^q U_t^T \nabla^2 f_t(U_t x) U_t$ , a sum of outer products

## How AMPL Computes Hessians

### **Detect partially separable structure**

Walk expression tree

Use a hashing scheme to spot common subexpressions

... may be useful even when Hessian is only approximated

### **Compute derivative information**

General or partially separable computations

Dense or sparse

Full or lower triangle

... using general and/or partially separable approach

## Interior-Point Methods

### *To solve*

Minimize  $f(x)$   
Subject to  $h_i(x) \geq 0, \quad i=1, \dots, m$

### *apply Newton's method to the optimality conditions*

$\nabla f(x) = \nabla h(x)^T y$   
 $h(x) = w$   
 $WYe = \mu e$

### *leading to a linear system of the form*

$$\begin{bmatrix} -\nabla^2(f(x) - h(x)^T y) & \nabla h(x)^T \\ \nabla h(x) & WY^{-1} \end{bmatrix} \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} = \dots$$

## Developing Interior-Point Methods with AMPL

### *Write an AMPL driver*

Use appropriate calls to get Hessian of Lagrangian

### *Convert some test problems*

CUTE (734)            COPS (17)  
Schittkowsky (195)    Hock & Schittkowsky (119)  
Netlib (40)            Vanderbei (29 groups)  
... *index at [www.sor.princeton.edu/~rvdb/ampl/nlmodels/](http://www.sor.princeton.edu/~rvdb/ampl/nlmodels/)*

### *Get some results*

Rapid development of competitive interior-point solvers  
— LOQO, KNITRO, MOSEK  
Addition of 2nd-derivative options to other kinds of solvers  
— CONOPT, SNOPT (?), PATHNLP

## Complementarity Problems

### *Definition*

Collections of complementarity conditions:

- Two inequalities must hold,  
at least one of them with equality

### *Applications*

Equilibrium problems in economics and engineering

Optimality conditions for nonlinear programs,  
bi-level linear programs, bimatrix games, . . .

## Classical Linear Complementarity

### *Economic equilibrium*

```
set PROD; # products
set ACT; # activities

param cost {ACT} > 0; # cost per unit of each activity
param demand {PROD} >= 0; # units of demand for each product
param io {PROD,ACT} >= 0; # units of each product from
# 1 unit of each activity

var Price {i in PROD};
var Level {j in ACT};

subject to Pri_Compl {i in PROD}:
    Price[i] >= 0 complements
        sum {j in ACT} io[i,j] * Level[j] >= demand[i];
subject to Lev_Compl {j in ACT}:
    Level[j] >= 0 complements
        sum {i in PROD} Price[i] * io[i,j] <= cost[j];
```

*... complementary slackness conditions  
for an equivalent linear program*



## Mixed Linear Complementarity

### *Economic equilibrium with bounded variables*

```
set PROD; # products
set ACT; # activities

param cost {ACT} > 0; # cost per unit
param demand {PROD} >= 0; # units of demand

param io {PROD,ACT} >= 0; # units of product per unit of activity

param level_min {ACT} > 0; # min allowed level for each activity
param level_max {ACT} > 0; # max allowed level for each activity

var Price {i in PROD};
var Level {j in ACT};

subject to Pri_Compl {i in PROD}:
    Price[i] >= 0 complements
        sum {j in ACT} io[i,j] * Level[j] >= demand[i];

subject to Lev_Compl {j in ACT}:
    level_min[j] <= Level[j] <= level_max[j] complements
        cost[j] - sum {i in PROD} Price[i] * io[i,j];
```

*... complementarity conditions  
for optimality of an equivalent bounded linear program*

## Mixed Nonlinear Complementarity

### *Economic equilibrium with price-dependent demands*

```
set PROD; # products
set ACT; # activities

param cost {ACT} > 0; # cost per unit
param demand {PROD} >= 0; # units of demand

param io {PROD,ACT} >= 0; # units of product per unit of activity
param demzero {PROD} > 0; # intercept and slope of the demand
param demrate {PROD} >= 0; # as a function of price

var Price {i in PROD};
var Level {j in ACT};

subject to Pri_Compl {i in PROD}:
    Price[i] >= 0 complements
        sum {j in ACT} io[i,j] * Level[j]
        >= demzero[i] + demrate[i] * Price[i];

subject to Lev_Compl {j in ACT}:
    Level[j] >= 0 complements
        sum {i in PROD} Price[i] * io[i,j] <= cost[j];
```

*... not equivalent to a linear program*

## Operands to complements: always 2 inequalities

### *Two single inequalities*

*single-ineq1* complements *single-ineq2*

Both inequalities must hold, at least one at equality

### *One double inequality*

*double-ineq* complements *expr*

*expr* complements *double-ineq*

The double-inequality must hold, and

if at lower limit then  $expr \geq 0$

if at upper limit then  $expr \leq 0$

if between limits then  $expr = 0$

## Influence on Solver Development

### *“Square” problems*

# of variables =

# of complementarity constraints + # of equality constraints

Transformation to a simpler canonical form is possible

### *MPECs*

Mathematical programs with equilibrium constraints

No restriction on numbers of variables & constraints

Objective functions permitted

### *Consequences for developers*

People *can* write MPECs in AMPL, so they *do*

Demand for adapted solvers is increased

— interior (Vanderbei) & SQP (Fletcher & Leyffer) methods

## Future Modeling Language Influences

### *Quadratic expressions*

Automatic detection of quadratic terms & extraction of Hessian matrix  
Original motivation? *Convex quadratic objective, linear constraints*

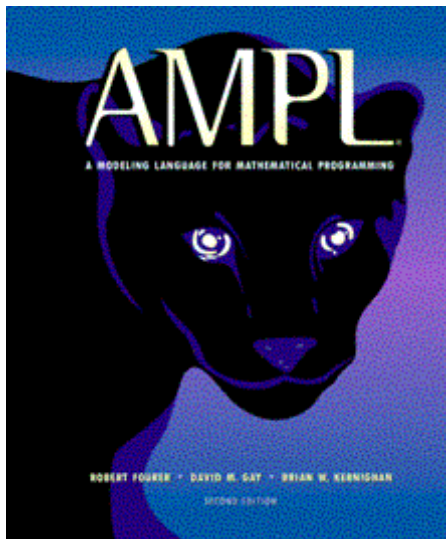
### *Matrix functions and constraints*

Determinant, eigenvalues  
Positive semidefinite  
Original motivation? *Semidefinite programming*

### *Actual nonlinear expressions as input to solvers*

Recursive walk of AMPL's expression tree  
Conversion to the form that the solver wants  
Original motivation? *Global optimization*

## AMPL Book **2nd Edition** Now Available



## **2nd Edition Features**

### *New chapters*

Database access	Command scripts
Modeling commands	Interactions with solvers
Display commands	Complementarity problems

*... all extensions previously only described roughly at web site*

### *Updates and improvements*

Existing chapters extensively revised  
Updated reference manual provided as appendix

*... and at half the recent price of the 1st edition!*

*... See [www.amp1.com/BOOK/](http://www.amp1.com/BOOK/)*